

Econometrics Field Exam

Department of Economics, University of California - Berkeley

August 2019

Please choose three questions to answer. Please use a separate blue book for each answered question. Write your name on each blue book. Answer as completely as you are able. Good luck!

[Q1] A dependent variable y_i is generated by a linear regression equation

$$y_i = x_i' \beta_0 + \varepsilon_i,$$

given an observed p -dimensional regression vector x_i , unobserved error term ε_i , and unknown coefficient vector β_0 . The errors ε_i are assumed to be independent of x_i with density function $f(\varepsilon)$ that is assumed to be positive everywhere, uniformly bounded, and smooth (i.e., lots of continuous derivatives), and has zero median, i.e.

$$\Pr\{\varepsilon_i \leq 0\} = 1/2.$$

Given a random sample of size N from this model, consider a penalized version of the usual LAD estimator:

$$\begin{aligned} \hat{\beta} &= \arg \min_{b \in \mathbb{R}^p} P_N(b) \\ &\equiv \arg \min_{b \in \mathbb{R}^p} \left(\left(\frac{1}{N} \sum_{i=1}^N |y_i - x_i' b| \right) + \frac{1}{2N} (b - \delta_0)' A_0 (b - \delta_0) \right) \\ &\equiv \arg \min_{b \in \mathbb{R}^p} \left(S_N(b) + \frac{1}{2N} (b - \delta_0)' A_0 (b - \delta_0) \right), \end{aligned}$$

where $S_N(b)$ is the usual LAD criterion function and δ_0 is a known "prior guess" of the unknown β_0 and A_0 is a known, positive-definite weight matrix.

- Under what additional conditions (if any) will $\hat{\beta}$ be consistent for β_0 ?
- Assume that the usual "approximate first-order condition"

$$\sqrt{N} \frac{\partial^- P_N(\hat{\beta})}{\partial b} = o_p(1),$$

where $\partial^- P_N(b)/\partial b$ is the subgradient of $P_N(b)$. Also assume the following "approximate mean-value expansion" holds:

$$\sqrt{N} \frac{\partial^- S_N(\hat{\beta})}{\partial b} = \sqrt{N} \frac{\partial^- S_N(\beta_0)}{\partial b} + H_0 \sqrt{N} (\hat{\beta} - \beta_0) + o_p(1),$$

where H_0 is the appropriate "Hessian" matrix for LAD regression, assumed invertible. Under these additional restrictions, derive the form of the asymptotic distribution of $\hat{\beta}$, assuming

it is consistent for β_0 . You need not check regularity conditions, but please make your expressions as explicit as possible (including the correct expression for H_0).

(c) Now suppose the penalized estimator $\hat{\beta}$ is defined as

$$\begin{aligned}\hat{\beta} &= \arg \min_{b \in \mathbb{R}^1} Q_N(b) \\ &\equiv \arg \min_{b \in \mathbb{R}^1} \left(\left(\frac{1}{N} \sum_{i=1}^N |y_i - x'_i b| \right) + \frac{1}{2\sqrt{N}} (b - \delta_0)' A_0 (b - \delta_0) \right) \\ &\equiv \arg \min_{b \in \mathbb{R}^1} \left(S_N(b) + \frac{1}{2\sqrt{N}} (b - \delta_0)' A_0 (b - \delta_0) \right),\end{aligned}$$

i.e., the original penalty term is multiplied by \sqrt{N} . Under what additional conditions (if any) will $\hat{\beta}$ be consistent for β_0 ?

(d) Again assuming that

$$\sqrt{N} \frac{\partial^- Q_N(\hat{\beta})}{\partial b} = o_p(1),$$

where $\partial^- Q_N(b)/\partial b$ is the subgradient of $Q_N(b)$, and that

$$\sqrt{N} \frac{\partial^- S_N(\hat{\beta})}{\partial b} = \sqrt{N} \frac{\partial^- S_N(\beta_0)}{\partial b} + H_0 \sqrt{N} (\hat{\beta} - \beta_0) + o_p(1),$$

derive the form of the asymptotic distribution of $\hat{\beta}$, assuming $\hat{\beta}$ is consistent for β_0 .

[Q2] Let $\{R_i\}_{i=1}^N$ be a simple random sample of the 1×3 vector $R_i = (X_i, Y_i, Z_i)$. We assume that

$$Y_i = Z_i \beta_0 + U_i, \quad \mathbb{E}[U_i | X_i] = 0, \quad (1)$$

with $Z_i \in \{0, 1\}$ binary and

$$\Pr(Z_i = 1 | X_i = x) = \Phi(x\gamma_0) \quad (2)$$

with $\Phi(\cdot)$ the cumulative distribution function of a standard normal. You may assume that other “standard” regularity conditions hold as well.

Consider the following two-step estimation procedure. First, apply maximum likelihood to the probit model (2), obtain $\hat{\gamma}$ and construct $\hat{Z}_i \stackrel{def}{=} \Phi(X_i \hat{\gamma})$ for $i = 1, \dots, N$. Second, compute the least squares fit of Y_i onto \hat{Z}_i :

$$\hat{\beta}_{TS} = \frac{\sum_{i=1}^N Y_i \hat{Z}_i}{\sum_{i=1}^N \hat{Z}_i^2}. \quad (3)$$

This procedure is analogous two-stage least squares, with the first stage based upon the probit instead of the linear probability model.

(a) Construct a moment function

$$\psi(R, \gamma, \beta) = \begin{bmatrix} \psi_1(R, \gamma) \\ \psi_2(R, \gamma, \beta) \end{bmatrix}$$

such that the corresponding method-of-moments estimate of (γ_0, β_0) , i.e., the solution to

$$\sum_{i=1}^N \psi \left(R_i, \hat{\gamma}, \hat{\beta}_{TS} \right) = 0,$$

is identical to that of the two step procedure described above.

(b) Verify that your moment function is valid, in the sense that

$$\mathbb{E} [\psi (R, \gamma_0, \beta_0)] = 0.$$

(c) Consider the alternative, infeasible, one-step estimator $\hat{\beta}_{OS}$ which replaces \hat{Z}_i in (3) with the true conditional probability $Z_{0i} \stackrel{def}{=} \Phi (X_i \gamma_0)$. Compare the asymptotic variances of $\hat{\beta}_{TS}$ and $\hat{\beta}_{OS}$. Provide a characterization of the efficiency loss, if any, associated with having to estimate γ_0 .

(d) Now assume that (2) is no longer valid (i.e., that the probit first stage is misspecified such that there is no γ_0 such that (2) holds for all $x \in \mathbb{X}$). For example it might be that

$$\Pr (Z_i = 1 | X_i = x) = \Phi (x\gamma_0 + x^2\delta_0).$$

Is the two-step estimator consistent under misspecification of the first stage (in general)? Explain.

(e) Consider the two-step instrumental variables estimator with $\psi_1 (R, \gamma)$ as in part (a) above, but now

$$\psi_2 (R_i, \gamma, \beta) = (Y_i - Z_i\beta) \Phi (X_i\gamma).$$

Does consistency of this estimator require both (1) and (2) or just the former or just the latter? Explain.

(f) Consider a second instrumental variables estimator with

$$\psi_2 (R_i, \gamma, \beta) = (Y_i - Z_i\beta) X_i$$

and $\psi_1 (R, \gamma)$ as in part (a) above. Assume that $\mathbb{V} (U_i | X_i = x) = \sigma^2$ for all $x \in \mathbb{X}$. Would you (generally) expect that the estimate of β_0 from part (e) to be more precisely, or less precisely, determined than the one based on the above moment function? Explain.

[Q3] Suppose $\{y_t : 1 \leq t \leq T\}$ is an observed strictly stationary time series generated by the (AR(1)) model

$$y_t = \sum_{i=0}^{\infty} \phi^i \varepsilon_{t-i},$$

where $\phi \in (-1, 1)$ and $\varepsilon_t \sim i.i.d. \mathcal{N}(0, 1)$.

As estimators of $\theta = \phi^2 \in [0, 1)$, consider

$$\hat{\theta} = \hat{\phi}^2, \quad \hat{\phi} = \frac{\sum_{t=2}^T y_{t-1} y_t}{\sum_{t=2}^T y_{t-1}^2},$$

$$\tilde{\theta} = \frac{\sum_{t=3}^T y_{t-2} y_t}{\sum_{t=3}^T y_{t-2}^2},$$

and

$$\check{\theta} = \max(\tilde{\theta}, 0).$$

It can be shown that, for $k \in \{1, 2\}$,

$$\frac{1}{T} \sum_{t=k+1}^T y_{t-k}^2 \rightarrow_p E(y_{t-k}^2)$$

and

$$\frac{1}{\sqrt{T}} \sum_{t=k+1}^T y_{t-k}(y_t - \phi^k y_{t-k}) \rightarrow_d \mathcal{N} \left(0, \lim_{T \rightarrow \infty} \text{Var} \left[\frac{1}{\sqrt{T}} \sum_{t=k+1}^T y_{t-k}(y_t - \phi^k y_{t-k}) \right] \right).$$

- (a) Find the limiting distribution (after appropriate centering and rescaling) of $\hat{\theta}$.
- (b) Find the limiting distribution of $\tilde{\theta}$.
- (c) Find the limiting distribution of $\check{\theta}$.
- (d) Rank the estimators from (a)-(c) in terms of (asymptotic) efficiency.

[Q4] Suppose $\{y_t : -1 \leq t \leq T\}$ is an observed strictly stationary time series generated by the (AR(1)) model

$$y_t = \varepsilon_t + \theta_0 \varepsilon_{t-1},$$

where $\theta_0 \in (-1, 1)$ and $\varepsilon_t \sim i.i.d. \mathcal{N}(0, 1)$.

- (a) Let $x_t = (y_t, y_{t-1}, y_{t-2})'$ and define the function

$$h(x_t, \theta) = \begin{bmatrix} y_{t-1}y_t - \theta \\ y_{t-2}y_t \end{bmatrix}.$$

Show that $\Theta = \{\theta_0\}$, where $\Theta = \{\theta : E[h(x_t, \theta)] = 0\}$.

Let

$$\hat{\theta}_W = \arg \min_{\theta} g_T(\theta)' W g_T(\theta), \quad g_T(\theta) = \frac{1}{T} \sum_{t=1}^T h(x_t, \theta),$$

where W is a symmetric, positive definite 2×2 matrix.

It can be shown that

$$\frac{1}{\sqrt{T}} \sum_{t=1}^T h(x_t, \theta_0) \rightarrow_d \mathcal{N} \left(0, \lim_{T \rightarrow \infty} \text{Var} \left[\frac{1}{\sqrt{T}} \sum_{t=1}^T h(x_t, \theta_0) \right] \right).$$

- (b) It can be shown that

$$\sqrt{T}(\hat{\theta}_W - \theta_0) \rightarrow_d \mathcal{N}(0, \omega_W^2),$$

where ω_W^2 is some function of ϕ_0 and W . Verify this claim and express ω_W^2 in terms of θ_0 and W .

- (c) Find W^* , a value of W for which ω_W^2 is minimal, and express $\omega_{W^*}^2$ in terms of θ_0 .

(d) Propose a feasible estimator $\hat{\theta}$ (i.e., an estimator $\hat{\theta}$ that can be computed without knowledge of θ_0) satisfying

$$\sqrt{T}(\hat{\theta} - \theta_0) \rightarrow_d \mathcal{N}(0, \omega_{W^*}^2).$$